

NAG Toolbox for MATLAB

g07bb

1 Purpose

g07bb computes maximum likelihood estimates and their standard errors for parameters of the Normal distribution from grouped and/or censored data.

2 Syntax

```
[xmu, xsig, sexmu, sexsig, corr, dev, nob, nit, ifail] = g07bb(method,  
x, xc, ic, xmu, xsig, tol, maxit, 'n', n)
```

3 Description

A sample of size n is taken from a Normal distribution with mean μ and variance σ^2 and consists of grouped and/or censored data. Each of the n observations is known by a pair of values (L_i, U_i) such that:

$$L_i \leq x_i \leq U_i.$$

The data is represented as particular cases of this form:

exactly specified observations occur when $L_i = U_i = x_i$,

right-censored observations, known only by a lower bound, occur when $U_i \rightarrow \infty$,

left-censored observations, known only by an upper bound, occur when $L_i \rightarrow -\infty$,

and interval-censored observations when $L_i < x_i < U_i$.

Let the set A identify the exactly specified observations, sets B and C identify the observations censored on the right and left respectively, and set D identify the observations confined between two finite limits. Also let there be r exactly specified observations, i.e., the number in A . The probability density function for the standard Normal distribution is

$$Z(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}x^2\right), \quad -\infty < x < \infty$$

and the cumulative distribution function is

$$P(X) = 1 - Q(X) = \int_{-\infty}^X Z(x) dx.$$

The log-likelihood of the sample can be written as:

$$L(\mu, \sigma) = -r \log \sigma - \frac{1}{2} \sum_A \{(x_i - \mu)/\sigma\}^2 + \sum_B \log(Q(l_i)) + \sum_C \log(P(u_i)) + \sum_D \log(p_i)$$

where $p_i = P(u_i) - P(l_i)$ and $u_i = (U_i - \mu)/\sigma$, $l_i = (L_i - \mu)/\sigma$.

Let

$$S(x_i) = \frac{Z(x_i)}{Q(x_i)}, \quad S_1(l_i, u_i) = \frac{Z(l_i) - Z(u_i)}{p_i}$$

and

$$S_2(l_i, u_i) = \frac{u_i Z(u_i) - l_i Z(l_i)}{p_i},$$

then the first derivatives of the log-likelihood can be written as:

$$\frac{\partial L(\mu, \sigma)}{\partial \mu} = L_1(\mu, \sigma) = \sigma^{-2} \sum_A (x_i - \mu) + \sigma^{-1} \sum_B S(l_i) - \sigma^{-1} \sum_C S(-u_i) + \sigma^{-1} \sum_D S_1(l_i, u_i)$$

and

$$\frac{\partial L(\mu, \sigma)}{\partial \sigma} = L_2(\mu, \sigma) = -r\sigma^{-1} + \sigma^{-3} \sum_A (x_i - \mu)^2 + \sigma^{-1} \sum_B l_i S(l_i) - \sigma^{-1} \sum_C u_i S(-u_i) - \sigma^{-1} \sum_D S_2(l_i, u_i)$$

The maximum likelihood estimates, $\hat{\mu}$ and $\hat{\sigma}$, are the solution to the equations:

$$L_1(\hat{\mu}, \hat{\sigma}) = 0 \quad (1)$$

and

$$L_2(\hat{\mu}, \hat{\sigma}) = 0 \quad (2)$$

and if the second derivatives $\frac{\partial^2 L}{\partial^2 \mu}$, $\frac{\partial^2 L}{\partial \mu \partial \sigma}$ and $\frac{\partial^2 L}{\partial^2 \sigma}$ are denoted by L_{11} , L_{12} and L_{22} respectively, then estimates of the standard errors of $\hat{\mu}$ and $\hat{\sigma}$ are given by:

$$\text{se}(\hat{\mu}) = \sqrt{\frac{-L_{22}}{L_{11}L_{22} - L_{12}^2}}, \quad \text{se}(\hat{\sigma}) = \sqrt{\frac{-L_{11}}{L_{11}L_{22} - L_{12}^2}}$$

and an estimate of the correlation of $\hat{\mu}$ and $\hat{\sigma}$ is given by:

$$\frac{L_{12}}{\sqrt{L_{11}L_{22}}}.$$

To obtain the maximum likelihood estimates the equations (1) and (2) can be solved using either the Newton–Raphson method or the Expectation-Maximization (EM) algorithm of Dempster *et al.* 1977.

Newton–Raphson Method

This consists of using approximate estimates $\tilde{\mu}$ and $\tilde{\sigma}$ to obtain improved estimates $\tilde{\mu} + \delta\tilde{\mu}$ and $\tilde{\sigma} + \delta\tilde{\sigma}$ by solving

$$\delta\tilde{\mu}L_{11} + \delta\tilde{\sigma}L_{12} + L_1 = 0,$$

$$\delta\tilde{\mu}L_{12} + \delta\tilde{\sigma}L_{22} + L_2 = 0,$$

for the corrections $\delta\tilde{\mu}$ and $\delta\tilde{\sigma}$.

EM Algorithm

The expectation step consists of constructing the variable w_i as follows:

$$\text{if } i \in A, \quad w_i = x_i \quad (3)$$

$$\text{if } i \in B, \quad w_i = E(x_i \mid x_i > L_i) = \mu + \sigma S(l_i) \quad (4)$$

$$\text{if } i \in C, \quad w_i = E(x_i \mid x_i < U_i) = \mu - \sigma S(-u_i) \quad (5)$$

$$\text{if } i \in D, \quad w_i = E(x_i \mid L_i < x_i < U_i) = \mu + \sigma S_1(l_i, u_i) \quad (6)$$

the maximization step consists of substituting (3), (4), (5) and (6) into (1) and (2) giving:

$$\hat{\mu} = \sum_{i=1}^n \hat{w}_i / n \quad (7)$$

and

$$\hat{\sigma}^2 = \sum_{i=1}^n (\hat{w}_i - \hat{\mu})^2 / \left\{ r + \sum_B T(\hat{l}_i) + \sum_C T(-\hat{u}_i) + \sum_D T_1(\hat{l}_i, \hat{u}_i) \right\} \quad (8)$$

where

$$T(x) = S(x)\{S(x) - x\}, \quad T_1(l, u) = S_1^2(l, u) + S_2(l, u)$$

and where \hat{w}_i , \hat{l}_i and \hat{u}_i are w_i , l_i and u_i evaluated at $\hat{\mu}$ and $\hat{\sigma}$. Equations (3) to (8) are the basis of the *EM* iterative procedure for finding $\hat{\mu}$ and $\hat{\sigma}^2$. The procedure consists of alternately estimating $\hat{\mu}$ and $\hat{\sigma}^2$ using (7) and (8) and estimating $\{\hat{w}_i\}$ using (3) to (6).

In choosing between the two methods a general rule is that the Newton–Raphson method converges more quickly but requires good initial estimates whereas the *EM* algorithm converges slowly but is robust to the initial values. In the case of the censored Normal distribution, if only a small proportion of the observations are censored then estimates based on the exact observations should give good enough initial estimates for the Newton–Raphson method to be used. If there are a high proportion of censored observations then the *EM* algorithm should be used and if high accuracy is required the subsequent use of the Newton–Raphson method to refine the estimates obtained from the *EM* algorithm should be considered.

4 References

Dempster A P, Laird N M and Rubin D B 1977 Maximum likelihood from incomplete data via the *EM* algorithm (with discussion) *J. Roy. Statist. Soc. Ser. B* **39** 1–38

Swan A V 1969 Algorithm AS16. Maximum likelihood estimation from grouped and censored normal data *Appl. Statist.* **18** 110–114

Wolynetz M S 1979 Maximum likelihood estimation from confined and censored normal data *Appl. Statist.* **28** 185–195

5 Parameters

5.1 Compulsory Input Parameters

1: **method** – string

Indicates whether the Newton–Raphson or *EM* algorithm should be used.

If **method** = 'N', then the Newton–Raphson algorithm is used.

If **method** = 'E', then the *EM* algorithm is used.

Constraint: **method** = 'N' or 'E'.

2: **x(n)** – double array

The observations x_i , L_i or U_i , for $i = 1, 2, \dots, n$.

If the observation is exactly specified – the exact value, x_i .

If the observation is right-censored – the lower value, L_i .

If the observation is left-censored – the upper value, U_i .

If the observation is interval-censored – the lower or upper value, L_i or U_i , (see **xc**).

3: **xc(n)** – double array

If the j th observation, for $j = 1, 2, \dots, n$ is an interval-censored observation then **xc(j)** should contain the complementary value to **x(j)**, that is, if **x(j)** < **xc(j)**, then **xc(j)** contains upper value, U_i , and if **x(j)** > **xc(j)**, then **xc(j)** contains lower value, L_i . Otherwise if the j th observation is exact or right- or left-censored **xc(j)** need not be set.

Note: if **x(j)** = **xc(j)** then the observation is ignored.

4: **ic(n)** – int32 array

ic(i) contains the censoring codes for the i th observation, for $i = 1, 2, \dots, n$.

If **ic(i)** = 0, the observation is exactly specified.

If **ic(i)** = 1, the observation is right-censored.

If $\mathbf{ic}(i) = 2$, the observation is left-censored.

If $\mathbf{ic}(i) = 3$, the observation is interval-censored.

Constraint: $\mathbf{ic}(i) = 0, 1, 2$ or 3 , for $i = 1, 2, \dots, n$.

5: **xmu – double scalar**

If $\mathbf{xsig} > 0.0$ the initial estimate of the mean, μ ; otherwise **xmu** need not be set.

6: **xsig – double scalar**

Specifies whether an initial estimate of μ and σ are to be supplied.

$\mathbf{xsig} > 0.0$

xsig is the initial estimate of σ and **xmu** must contain an initial estimate of μ .

$\mathbf{xsig} \leq 0.0$

Onitil estimates of **xmu** and **xsig** are calculated internally from:

- (a) the exact observations, if the number of exactly specified observations is ≥ 2 ; or
- (b) the interval-censored observations; if the number of interval-censored observations is ≥ 1 ; or
- (c) they are set to 0.0 and 1.0 respectively.

7: **tol – double scalar**

The relative precision required for the final estimates of μ and σ . Convergence is assumed when the absolute relative changes in the estimates of both μ and σ are less than **tol**.

If **tol** = 0.0, then a relative precision of 0.000005 is used.

Constraint: *machine precision* < **tol** ≤ 1.0 or **tol** = 0.0.

8: **maxit – int32 scalar**

The maximum number of iterations.

If **maxit** ≤ 0 , then a value of 25 is used.

5.2 Optional Input Parameters

1: **n – int32 scalar**

Default: The dimension of the arrays **x**, **xc**, **ic**. (An error is raised if these dimensions are not equal.)

n , the number of observations.

Constraint: $n \geq 2$.

5.3 Input Parameters Omitted from the MATLAB Interface

wk

5.4 Output Parameters

1: **xmu – double scalar**

The maximum likelihood estimate, $\hat{\mu}$, of μ .

2: **xsig – double scalar**

The maximum likelihood estimate, $\hat{\sigma}$, of σ .

3: **sexmu – double scalar**

The estimate of the standard error of $\hat{\mu}$.

4: **sexsig – double scalar**

The estimate of the standard error of $\hat{\sigma}$.

5: **corr – double scalar**

The estimate of the correlation between $\hat{\mu}$ and $\hat{\sigma}$.

6: **dev – double scalar**

The maximized log-likelihood, $L(\hat{\mu}, \hat{\sigma})$.

7: **nobs(4) – int32 array**

The number of the different types of each observation;

nobs(1) contains number of right-censored observations.

nobs(2) contains number of left-censored observations.

nobs(3) contains number of interval-censored observations.

nobs(4) contains number of exactly specified observations.

8: **nit – int32 scalar**

The number of iterations performed.

9: **ifail – int32 scalar**

0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

On entry, **method** \neq 'N' or 'E',
 or **n** < 2,
 or **ic**(*i*) \neq 0, 1, 2 or 3, for some *i*,
 or **tol** < 0.0,
 or $0.0 < \text{tol} < \text{machine precision}$,
 or **tol** > 1.0.

ifail = 2

The chosen method failed to converge in **maxit** iterations. You should either increase **tol** or **maxit** or, if using the *EM* algorithm try using the Newton–Raphson method with initial values those returned by the current call to g07bb. All returned values will be reasonable approximations to the correct results if **maxit** is not very small.

ifail = 3

The chosen method is diverging. This will be due to poor initial values. You should try different initial values.

ifail = 4

g07bb was unable to calculate the standard errors. This can be caused by the method starting to diverge when the maximum number of iterations was reached.

7 Accuracy

The accuracy is controlled by the parameter **tol**.

If high precision is requested with the *EM* algorithm then there is a possibility that, due to the slow convergence, before the correct solution has been reached the increments of $\hat{\mu}$ and $\hat{\sigma}$ may be smaller than **tol** and the process will prematurely assume convergence.

8 Further Comments

The process is deemed divergent if three successive increments of μ or σ increase.

9 Example

[illegible]

```
        int32(1);
        int32(2);
        int32(2);
        int32(3)];
xmu = 4;
xsig = 1;
tol = 5e-05;
maxit = int32(50);
[xmuOut, xsigOut, sexmu, sexsig, corr, dev, nob, nit, ifail] = ...
    g07bb(method, x, xc, ic, xmu, xsig, tol, maxit)
```

```
xmuOut =
    4.4924
xsigOut =
    1.0196
sexmu =
    0.2606
sexsig =
    0.1940
corr =
    0.0160
dev =
   -22.2817
nob =
     3
     2
     1
    12
nit =
     5
ifail =
     0
```